

# Piglide Air Bearing Technology

NANOMETER PRECISION, MULTI-AXIS MOTION, STANDARD & CUSTOM DESIGNS



## Plglide

# The Step Ahead with Air Bearing Technology

#### **Frictionless High-Precision Positioning**

A direct-drive motor and high-resolution encoder can position a moving carriage supported by an air bearing to within nanometers in a linear application or within tenths of arcseconds in rotational applications. The lack of friction and mechanical contact means there is minimal hysteresis or reversal error, making it highly repeatable and ideal for many inspection and manufacturing operations. Stiction is virtually eliminated, improving resolution capabilities, position repeatability can be obtained within a few fundamental encoder counts. Similar precision can be obtained by piezo flexure guided stages, however over much smaller travel ranges.

#### **Velocity Stability and Scanning**

The lack of mechanical bearing elements means there is nothing to get in the way of smooth, controlled velocity (stability to better than 0.01%). Experiments and processes like inertial sensor testing, tomography, wafer scanning, and surface profiling require continuous motion at a tightly controlled speeds are best served by air bearing systems.

#### **High Guiding Accuracy**

Linear air bearing stages have incredibly straight and flat travels, measured in the 100's or 10's of nanometers and sub-arc-second pitch, roll, and yaw errors. Rotary stages have tilt (wobble) errors less than 1 arc-second. Additionally, the angular performance of an air bearing is remarkably repeatable. This guarantees optimal part quality and measurement reliability for applications such as optics inspection, semiconductor inspection, and medical device manufacturing.









### Air Bearing Technology

# The Step Ahead with the Full Range of PI Technologies

#### **Experience with Air Bearing Technology**

Pl is building on over 200 man-years of in-house air bearing experience and offers comprehensive precision air bearing motion control and positioning products and systems.

With 4 decades of experience in piezo nanopositioning systems design and motorized precision positioning equipment, the new air bearing systems capabilities are a natural and logical extension of Pl's precision motion offerings.

#### **Core Technology Inhouse**

Having all the core technologies available in-house allows PI to design and manufacture excellent products. Optimum performance is achieved by extensive simulations of relevant components, from the magnetic field for the motor layout, the FEM simulations of stages, to the control algorithm design. Keeping the number of parts low secures high reliability of the system.

#### Flexible Axis Configuration

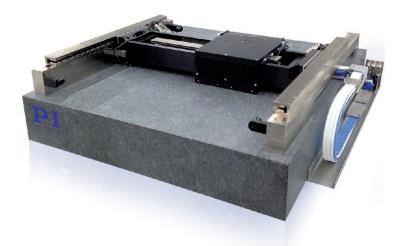
- Single axis linear stages
- Rotary stages
- XY Planar Scanners
- Non-motorized linear and rotary bearings
- Hemispherical bearings
- Rotary air bearing spindles

PI serves both the research and industrial markets.

#### Customization

Pl is in the unique position to cover the whole motion range from finger-tip sized nano-positioners to large scale stages with long travel ranges, through a plethora of different drive and guiding systems tailored exactly to the customer's needs.

By combining extremely responsive engineering consultative support and lean manufacturing techniques, PI is able to provide the highest quality customer service. Maximum performance of precision systems is achieved thru extensive design and analysis expertise, using equipment built inhouse with proprietary techniques.









### Plglide MB: Miniature Linear Air Bearing Stage

HIGH PERFORMANCE, CLEANROOM COMPATIBLE, CUSTOMIZABLE



### A-141 Series

- Table size 57mm x 83mm
- Overall height 38mm
- Travel lengths to 40 mm
- 3.5 kg max payload
- Non-contact fully preloaded air bearings
- Ironless cog-free linear motor
- Integral optical linear encoder
- Resolutions to 20nm
- Velocity to 0.5 m/sec
- Acceleration to 0.75 g

#### Overview

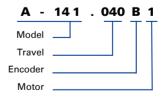
The Plglide MB air bearing stage is linear servo motor driven with fully preloaded air bearings and an integral optical linear encoder. This stage offers ultra-precision in a miniature package. The combination of non-contact components results in a frictionless motion platform that offers the highest performance, quality, and life. This stage is ideally suited for many high precision applications, such as metrology, photonics alignment, optics positioning, and scanning. The non-contact design also makes these stages ideal for cleanroom applications. There are no moving electrical cables to manage. The air bearing offers a locking design for the ultimate in position stability.

- Air preparation kits
- Single or multi-axis motion controller and servo drives
- Additional accessories available upon request



| Model                                       | A-141.040B1   |
|---|---|
| Travel                                      | 40 mm   |
| Drive System                                | Brushless linear servo motor, 3-phase   |
| Feedback System                             | Non-contact optical linear encoder  |
| Motor Bus Voltage                           | Up to 80 VDC  |
| Motor Force Constant                        | 2.1 N/A   |
| Motor Back EMF                              | 0.7 V/m/sec   |
| Motor Resistance<br>(@25°C, phase-to-phase) | 22.4 ohms   |
| Limit Switches                              | Differential, at each end of travel   |
| Home Index                                  | Near center of travel, repeatable to +/- 1 encoder count                                      |
| Maximum Velocity (1)                        | Up to 0.5 m/sec   |
| Maximum Acceleration (1)                    | Up to 0.75 g  |
| Maximum Payload (2)                         | 3.5 kg  |
| Accuracy (3)                                | +/-3.0 μm   |
| Repeatability                               | +/-0.2 μm   |
| Encoder Resolution (4)                      | 20 nm   |
| Straightness & Flatness (5)                 | < 1µm TIR over full travel  |
| Pitch & Yaw (5)                             | < 2 arc-sec TIR over full travel  |
| Stage Mass                                  | 0.6 kg  |
| Moving Mass                                 | 0.3 kg  |
| Cabling                                     | Internal, non-moving  |
| Operating Pressure (6)                      | 65 +/-5 psi (450 +/-35 kPa)   |
| Air Consumption                             | < 1.0 SCFM (28 SLPM)  |
| Air Quality                                 | Clean (filtered to 1.0 $\mu m$ or better) / Oil-free / Dry (-15 $^{\circ}\text{C}$ dew point) |
| Construction                                | Hardcoat Aluminum / SS Fasteners  |

- 1. Maximum velocity and acceleration based on stage capability, may be limited by controller or drive performance.
- 2. Assumes payload CG is centered no more than 50mm above the stage table.
- 3. Improved accuracy can be obtained with controller-based error compensation.
- 4. Encoder resolution can be changed upon request, please contact PI for a quote.
- 5. Dependent on the flatness of the surface to which the stage is mounted.
- 6. To protect stage from damage, an under-pressure air sensor tied to the controller E-stop input is recommended.



| Model | Travel      | Encoder <sup>(1)</sup>                  | Motor Wiring                      |
|-------|-------------|---|-----------------------------------|
| A-141 | 040 = 40 mm | B = 20 nm/count TTL A-<br>quad-B output | 1 = Standard motor option, 48 VDC |

1. Alternate encoder resolutions available on request.

### Ordering Example

Part# A-141.040B1 is a

Model: A-141 (Piglide MB miniature linear motorized air bearing stage)

Travel: 40 mm

Encoder: B (20 nm/count TTL A-quad-B output)

Motor Wiring: 1 (48 VDC)



## Plglide LC: Linear Air Bearing Stage

#### HIGH PERFORMANCE AFFORDABLE NANOPOSITIONING SYSTEM



#### A-110 Series

- Ideal for scanning or high-resolution positioning
- Cleanroom compatible
- Customizable
- Table size 160 mm x 200 mm
- Travel lengths to 400 mm
- 10 kg max payload
- Non-contact fully preloaded air bearings
- Ironless cog-free linear motor
- Integral optical linear encoder
- Resolutions to 1nm
- Velocity to 1 m/sec
- Acceleration to 1 g

#### Overview

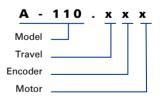
The Plglide LC series of stages are linear servo motor driven with fully preloaded air bearing and an integral optical linear encoder. The combination of these non-contact components results in a frictionless motion platform that offers the highest performance, quality and life. These stages are ideally suited for many high precision applications, such as metrology, photonics alignment, semiconductor, flat panel display and precision scanning applications. The non-contact design also makes these stages ideal for cleanroom applications.

- Air preparation kit
- Single or multi-axis motion controller and servo drives
- Additional accessories available on request
- XY stacks and custom configurations available upon request



| Model                                       | A-110.100     | A-110.200                             | A-110.300                       | A-110.400     |  |  |
|---|---------------|---------------------------------------|---------------------------------|---------------|--|--|
| Travel (limit to limit)                     | 100 mm        | 200 mm                                | 300 mm                          | 400 mm        |  |  |
| Drive System                                |               | Brushless linear servo motor, 3-phase |                                 |               |  |  |
| Feedback System                             |               | Non-contact option                    | cal linear encoder              |               |  |  |
| Motor Bus Voltage                           |               | Up to 80 VDC (4                       | 18 VDC nominal)                 |               |  |  |
| Motor Force Constant                        | 4.2 N/A       |                                       | 12 N/A                          |               |  |  |
| Motor Back EMF                              | 4.2 V/m/sec   |                                       | 12 V/m/sec                      |               |  |  |
| Motor Resistance<br>(@25°C, phase-to-phase) | 8.2 ohms      |                                       | 5.2 ohms                        |               |  |  |
| Limit Switches                              |               | Normall                               | ly closed                       |               |  |  |
| Home Switch                                 |               | Near end                              | d of travel                     |               |  |  |
| Maximum Velocity (1)                        |               | Up to                                 | 1 m/sec                         |               |  |  |
| Maximum Acceleration (1)                    |               | Up to 1 g                             |                                 |               |  |  |
| Maximum Payload (2)                         |               | 10                                    | kg                              |               |  |  |
| Accuracy (3)                                | +/-2.0 μm     | +/-2.0 μm                             | +/-2.5 μm                       | +/-3.0 μm     |  |  |
| Repeatability                               |               | +/-0.                                 | 5 μm                            |               |  |  |
| Encoder Resolution (4)                      |               | up to                                 | 1 nm                            |               |  |  |
| Straightness & Flatness (5)                 |               | < 0.1 µm / 25mm                       | 2μm TIR overall                 |               |  |  |
| Pitch & Yaw (5)                             | 2 arc-sec TIR | 2 arc-sec TIR                         | 4 arc-sec TIR                   | 6 arc-sec TIR |  |  |
| Stage Mass                                  | 7.5 kg        | 11 kg                                 | 12 kg                           | 14 kg         |  |  |
| Moving Mass                                 | 2.5 kg        | 2.6 kg                                |                                 |               |  |  |
| Cabling                                     | Internal      |                                       | External, moving loop           |               |  |  |
| Operating Pressure (6)                      |               | 65 (+/-5) psi (                       | (450 +/-35 kPa)                 |               |  |  |
| Air Consumption                             |               | < 1.0 SCFM                            | M (28 SLPM)                     |               |  |  |
| Air Quality                                 | Clean         | (filtered to 1.0 µm or bette          | r) / Oil-free / Dry (-15 °C dev | w point)      |  |  |
| Construction                                |               | Hardcoat Alumir                       | num / SS Fasteners              |               |  |  |

- Maximum velocity and acceleration based on stage capability, may be limited by controller or drive performance.
   Assumes payload CG is centered no more than 50mm above the stage table.
- 3. Improved accuracy can be obtained with controller-based error compensation.
- 4. Encoder resolution depends on options chosen and interpolation used.
- 5. Dependent on the flatness of the surface to which the stage is mounted.
- 6. To protect stage from damage, an under-pressure air sensor tied to the controller E-stop input is recommended.



| Model | Travel | Encoder (1)                         | Motor Wiring                      |
|-------|--------|-------------------------------------|-----------------------------------|
| A-110 | 100    | A = 20 μm/line sine output (1 Vp-p) | 1 = Standard motor option, 48 VDC |
|       | 200    |                                     |                                   |
|       | 300    |                                     |                                   |
|       | 400    |                                     |                                   |

1. Alternate encoder options, such as TTL quadrature output, are available on request.

#### **Ordering Example**

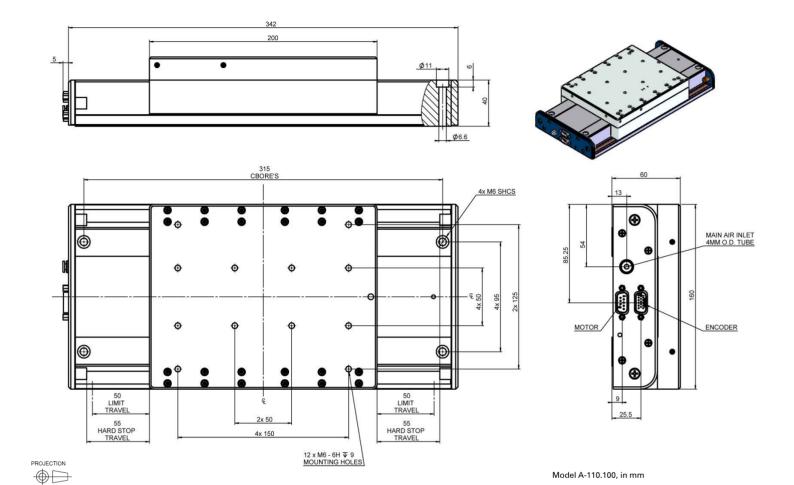
Part# A-110.300A1 is a

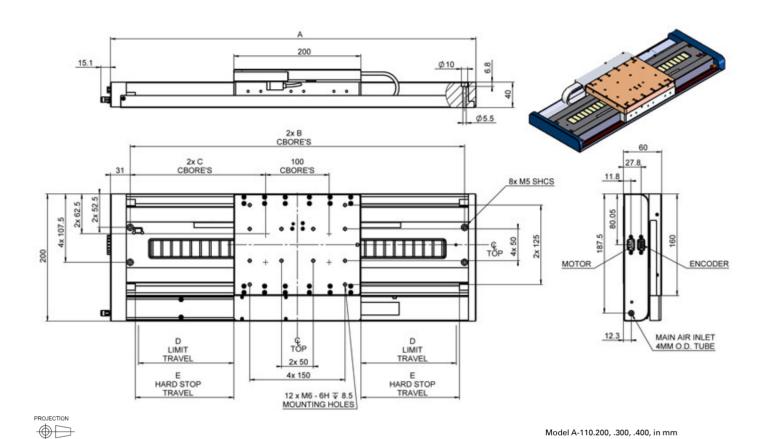
A-110 (PIglide LC linear motorized air bearing stage) Model:

Travel:

Encoder: A (20 µm/line sine output, 1 Vp-p)

Motor Wiring: 1 (48 VDC)





| Model     | А   | В   | С   | D   | Е   |
|-----------|-----|-----|-----|-----|-----|
| A-110.200 | 475 | 400 | 150 | 100 | 105 |
| A-110.300 | 575 | 526 | 213 | 150 | 155 |
| A-110.400 | 675 | 626 | 263 | 200 | 205 |



### Plglide HS: Planar Air Bearing Stage

#### ULTRA PERFORMANCE XY NANOPOSITIONING SYSTEM



#### Overview

The Plglide HS planar air-bearing stage has been designed to maximize throughput while providing the ultimate level of precision. This stage is ideal for wafer inspection and scribing applications, as well as other ultra-precision motion applications such as flat panel inspection.

Flexural coupling of the cross beam to the lower axis provides yaw-compliance without sacrificing system stiffness. The gantry axis cross beam incorporates dual linear motors and dual linear encoders. Ironless linear motors provide smooth motion and no cogging or attractive forces. Both incremental and absolute encoder options are available. The Plglide HS incorporates three high-accuracy linear encoders, one for the bridge axis and two for the gantry axis.

The PIglide HS can be coupled with a variety of industryleading digital controls and drives that offer advanced algorithms to improve dynamic performance and error compensation and a wide suite of software development tools.

#### A-322 Series

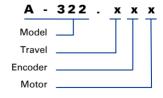
- Ideal for scanning or high-resolution positioning
- Clean room compatible
- Customizable
- Travel lengths to 500 mm x 1000 mm
- Load to 15 kg max
- Non-contact fully preloaded air bearings
- Resolution to 1 nm
- Velocity to 1 m/sec
- Acceleration to 1 g
- Straightness/Flatness to 0.25 μm
- Active yaw control and error compensation
- Dynamic mapping achieves near "laser" performance
- Active error compensation algorithms for straightness

- Air preparation kits
- Multi-axis motion controller and servo drives
- Machine bases
- Vibration isolation systems
- Additional accessories and customizations available on request



| Travel (limit to limit)   350 mm   | ncoder ninal) +/-15 nm   |  |  |  |
|--|--|--|--|--|
| Non-contact optical linear end   | ncoder ninal) +/-15 nm   |  |  |  |
| Motor Bus Voltage         Up to 80 VDC (48 VDC non Maximum Velocity (1)         Up to 1 m/sec           Maximum Acceleration (1)         Up to 1 g           Maximum Payload (2)         15 kg           Accuracy (3)         +/-1.0 μm           Repeatability         +/-50 nm           Servo Stability (5)         +/-10 nm           Velocity Stability (5)         +/-10 nm           Velocity Stability (5)         < 0.06% @ 80 mm/sec | ninal)<br>+/-15 nm   |  |  |  |
| Maximum Velocity (1)         Up to 1 m/sec           Maximum Acceleration (1)         Up to 1 g           Maximum Payload (2)         15 kg           Accuracy (3)         +/-1.0 μm           Repeatability         +/-50 nm           Servo Stability (5)         +/-10 nm           Velocity Stability (5)         < 0.06% @ 80 mm/sec  | +/-15 nm   |  |  |  |
| Maximum Acceleration (1)       Up to 1 g         Maximum Payload (2)       15 kg         Accuracy (3)       +/-1.0 μm         Repeatability       +/-50 nm         Servo Stability (5)       +/-10 nm         Velocity Stability (5)       < 0.06% @ 80 mm/sec   |  |  |  |  |
| Maximum Payload (2)       15 kg         Accuracy (3)       +/-1.0 μm         Repeatability       +/-50 nm         Servo Stability (5)       +/-10 nm         Velocity Stability (5)       < 0.06% @ 80 mm/sec  |  |  |  |  |
| Accuracy (3)       +/-1.0 μm         Repeatability       +/-50 nm         Servo Stability (5)       +/-10 nm         Velocity Stability (5)       < 0.06% @ 80 mm/sec  |  |  |  |  |
| Repeatability +/-50 nm  Servo Stability (5) +/-10 nm  Velocity Stability (5) < 0.06% @ 80 mm/sec  Encoder Resolution (4) Up to 1.0 nm  Flatness 2.0 µm TIR overall   |  |  |  |  |
| Servo Stability   (5)  |  |  |  |  |
| Velocity Stability $^{(5)}$ < 0.06% @ 80 mm/sec  Encoder Resolution $^{(4)}$ Up to 1.0 nm  Flatness $2.0 \ \mu m$ TIR overall  |  |  |  |  |
| Encoder Resolution <sup>(4)</sup> Up to 1.0 nm  Flatness  < 0.1 μm / 25 mm 2.0 μm TIR overall  |  |  |  |  |
| < 0.1 μm / 25 mm   2.0 μm TIR overall  | < 0.1% @ 80 mm/sec   |  |  |  |
| 2.0 µm TIR overall   |  |  |  |  |
| < 0.1 µm / 25 mm   | < 0.1 µm / 25mm<br>4.0 µm TIR overall  |  |  |  |
| Straightness <sup>(3)</sup> < 0.1 µm / 25 mm<br>1.0 µm TIR overall   | < 0.1 µm / 25 mm<br>1.0 µm TIR overall   |  |  |  |
| Pitch 4 arc-sec TIR  | 6 arc-sec TIR  |  |  |  |
| Yaw <sup>(3)</sup> 0.6 arc-sec TIR   | 0.4 arc-sec TIR  |  |  |  |
| XY Orthogonality +/-2 arc-sec  |  |  |  |  |
| Step and Settle $^{(1)}$ 20 mm step, settle to +/-0.1 $\mu$ m wit  | 10 mm step, settle to +/-0.1 $\mu$ m within 150 msec 20 mm step, settle to +/-0.1 $\mu$ m within 190 msec 50 mm step, settle to +/-0.1 $\mu$ m within 262 msec |  |  |  |
| Stage Mass 705 kg  |  |  |  |  |
| Moving Mass 13 kg  | 39 kg  |  |  |  |
| Operating Pressure <sup>(6)</sup> 65 (+/-5) psi (450 +/-35 k   | (Pa)   |  |  |  |
| Air Consumption < 2.0 SCFM (56 SLPN  | < 2.0 SCFM (56 SLPM)   |  |  |  |
| Air Quality Clean (filtered to 1.0µm or better) and oil-free   | Clean (filtered to 1.0µm or better) and oil-free / Dry (-15 °C dew point)  |  |  |  |
| Construction Hardcoat Aluminum with SS Fasteners   | Hardcoat Aluminum with SS Fasteners / Granite Base (7)   |  |  |  |

- Maximum velocity and acceleration based on stage capability, may be limited by controller or drive performance.
- 2. Assumes payload CG is centered no more than 50mm above the table.
- 3. Values shown obtained using controller-based error compensation.
- 4. Encoder resolution depends on options chosen and interpolation used.
- 5. Dependent on the machine base and isolation system to which the stage is mounted.
- 6. To protect stage from damage, an under-pressure air sensor tied to the controller E-stop input is
- 7. Other materials are available, please contact a PI Sales Engineer for more information.



| Model | Travel (X-Axis x Y-Axis) | Encoder <sup>(1)</sup>                             | Motor Wiring                      |
|-------|--------------------------|--|-----------------------------------|
| A-322 | A = 350 mm x 350 mm      | A = 20 μm/line incremental<br>Sine output (1 Vp-p) | 1 = Standard motor option, 48 VDC |
|       | B = 350 mm x 500 mm      | B = 1 nm absolute<br>BiSS serial output            |                                   |
|       | C = 500 mm x 500 mm      |  |                                   |
|       | D = 500 mm x 1000 mm     |  |                                   |

1. Alternate encoder options, such as TTL quadrature output, are available on request.

#### **Ordering Example**

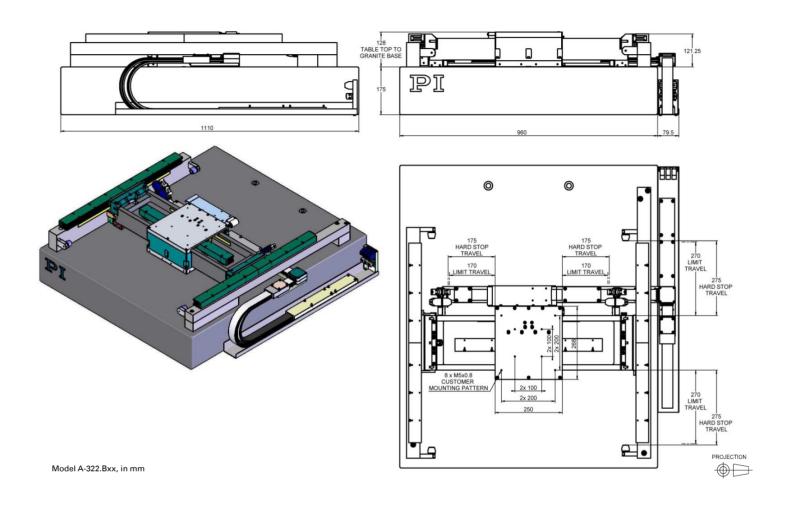
Part# <u>A-322.BB1</u> is a

Model: A-322 (Plglide HS planar motorized air bearing stage)

<u>Travel</u>: B (350 mm x 500 mm Encoder: B (1 nm absolute BiSS)

Motor Wiring: 1 (48 VDC)







### Plglide IS: Planar XY Air Bearing Stage

ULTRA PERFORMANCE. COMPACT XY NANOPOSITIONING SYSTEM



#### A-311 Series

- Ideal for scanning or high-resolution positioning
- Clean room compatible
- Customizable
- Travel lengths to 200mm x 200mm
- Load to 15kg max
- Non-contact fully preloaded air bearings
- Low profile design
- Resolution to 1nm
- Velocity to 1m/sec
- Acceleration to 1g

#### Overview

The Plglide IS planar XY air-bearing stage is a low profile, high precision alternative to stacked XY stages. The fully preloaded air bearing puck floats in both X and Y directions on a common base, providing smooth, frictionless motion. Ideal for inspection, laser marking, microscopy, scanning, and other precision motion applications. The efficient, compact design saves space in tight machine designs. Ironless linear motors provide smooth motion with no cogging or attractive forces. Optical linear encoders provide position feedback information down to 1nm, depending on interpolation.

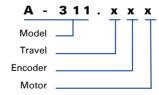
The Plglide IS can be coupled with a variety of industry-leading digital controls and drives that offer advanced algorithms to improve dynamic performance and error compensation and a wide suite of software development tools.

- Air preparation kits
- Multi-axis motion controller and servo drives
- Machine bases
- Vibration isolation systems
- Additional accessories and customizations available



| X-Axis (Lower Axis) Y-Axis (Upper Axis)                                    |   |  |  |  |  |
|--|---|--|--|--|--|
| 150 mm 150 mm  |   |  |  |  |  |
| Brushless linear servo motor, 3-phase                                      |   |  |  |  |  |
| Non-contact optical linear encoder   |   |  |  |  |  |
| Up to 80 VDC (48 VDC nominal)  |   |  |  |  |  |
| Up to 1  | m/sec   |  |  |  |  |
| 12.3   | N/A   |  |  |  |  |
| 10.1 V   | /m/sec  |  |  |  |  |
| 2 oh   | nms   |  |  |  |  |
| Up to  | Up to 1 g   |  |  |  |  |
| 15 kg  |   |  |  |  |  |
| +/-5.0 µm  |   |  |  |  |  |
| +/-0.5   | +/-0.5 μm   |  |  |  |  |
| Up to 1.0 nm   |   |  |  |  |  |
| <0.1µm / 25 mm,  | 1 μm TIR overall  |  |  |  |  |
| <0.1 $\mu$ m / 25mm, 1 $\mu$ m TIR overall                                 | <0.1µm / 25mm, 1 µm TIR overall   |  |  |  |  |
| 1 arc-s  | ec TIR  |  |  |  |  |
| 2 arc-s  | ec TIR  |  |  |  |  |
| 5 arc  | -sec  |  |  |  |  |
| 20   | kg  |  |  |  |  |
| 5 kg   | 2.5 kg  |  |  |  |  |
| 65 (+/-5) psi (450 +/-35 kPa)  |   |  |  |  |  |
| < 2.0 SCFM (56 SLPM)   |   |  |  |  |  |
| Clean (filtered to 1.0µm or better) and oil-free<br>Dry (-15 °C dew point) |   |  |  |  |  |
| Hardcoat Aluminum  | with SS Fasteners   |  |  |  |  |
|  | 150 mm  Brushless linear set  Non-contact optic  Up to 80 VDC (4  Up to 1  12.3  10.1 V/  2 oh  Up to 4  15  +/-5.0  +/-0.8  Up to 4  <0.1μm / 25 mm,  <0.1μm / 25 mm,  1 arc-s  2 arc-s  5 arc  20  5 kg  65 (+/-5) psi (4  < 2.0 SCFM  Clean (filtered to 1.0μm |  |  |  |  |

- 1. Maximum velocity and acceleration based on stage capability, may be limited by controller or drive performance.
- 2. Assumes payload CG is centered no more than  $50 \mathrm{mm}$  above the stage table.
- 3. Can be improved using controller-based error compensation.
- 4. Encoder resolution depends on options chosen and interpolation used.
- 5. Dependent on the machine base and isloation system to which the stage is mounted.
- 6. To protect stage from damage, an under-pressure air sensor tied to the controller E-stop input is recommended.



| Model | Travel (X-Axis x Y-Axis) | Encoder (1)  | Motor Wiring                      |  |
|-------|--------------------------|--|-----------------------------------|--|
| A-322 | A = 100 mm x 100 mm      | A = 20 μm/line incremental<br>Sine output (1 Vp-p) | 1 = Standard motor option, 48 VDC |  |
|       | B = 150 mm x 150 mm      |  |                                   |  |
|       | C = 200 mm x 200 mm      |  |                                   |  |

1. Alternate encoder options, such as TTL quadrature output, are available on request.

### Ordering Example

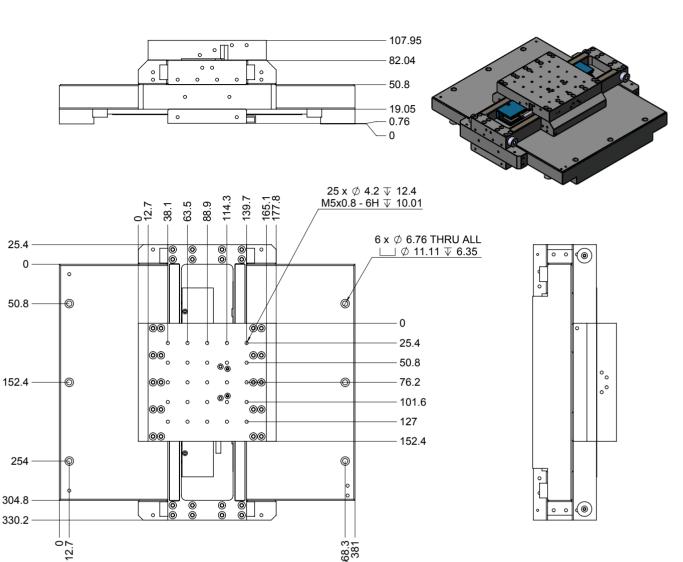
Part# <u>A-311.BA1 is</u> a

Model: A-311 (Piglide IS planar motorized air bearing stage)

<u>Travel</u>: B (150 mm x 150 mm)

Encoder: A (20 μm/line sine output, 1 Vp-p)

Motor Wiring: 1 (48 VDC)



PROJECTION

Model A-311.Bxx, in mm



### Plglide RB: Linear Air Bearing

FRICTIONLESS, IDEAL FOR POSITIONING, SCANNING, METROLOGY



### **A-10X Series**

- Ideal for scanning or high-resolution positioning
- Clean room compatible
- Table sizes up to 300mm x 300mm
- Travel lengths up to 1m
- Load to 775kg
- Straightness/Flatness to 0.5µm / 25mm
- Pitch/Roll/Yaw to 0.25 arc-sec / 25mm

For applications that require smooth, precise, linear motion, the Plglide RB series linear air bearings are right for you. These bearings can easily replace ball bearing and crossed roller bearing slides, and are simple to integrate and use.

They offer better straightness, angular deviation, and repeatability than ball bearing slides, especially for travel lengths over 4". In addition, because air bearings are inherently frictionless, they do not exhibit breakaway or running friction, even under their maximum loading. The totally noncontact, clean nature of air bearings means that they are virtually maintenance free and their accuracy won't degrade over time due to wear.

- Air preparation kit
- Mounting feet
- Custom configurations available upon request

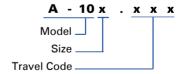


|       | Table Size<br>Length x Width | Travels Available |        | apacity<br>N) |
|-------|------------------------------|-------------------|--------|---------------|
| Model | (mm x mm)                    | (mm)              | Normal | Lateral       |
| A-101 | 50 x 50                      | 50 - 200          | 130    | 75            |
| A-102 | 50 x 100                     | 50 - 300          | 260    | 260           |
| A-103 | 75 x 75                      | 50 - 300          | 350    | 195           |
| A-104 | 75 x 115                     | 50 - 300          | 540    | 540           |
| A-105 | 100 x 100                    | 50 - 300          | 630    | 370           |
| A-106 | 100 x 150                    | 50 - 600          | 950    | 950           |
| A-107 | 150 x 150                    | 50 - 750          | 1580   | 790           |
| A-108 | 200 x 200                    | 50 - 1000         | 2950   | 1475          |
| A-109 | 300 x 300                    | 50 - 1000         | 7600   | 2210          |

Note: Load capacities listed assume supply pressure of 80 psi.

|                                 |  | Travels<br>to 300 mm | Travels<br>to 600 mm | Travels<br>to 1000 mm |
|---------------------------------|--|----------------------|----------------------|-----------------------|
| Straightness & Flatness (TIR)   | Short-term 0.5µm / 25mm  |                      |                      |                       |
| Straightness & Fratriess (Tilt) | Overall  | 2.5 μm               | 5.0 µm               | 10.0 μm               |
| Stability                       | +/- 0.05 μm  |                      |                      |                       |
| Pitch & Yaw (TIR)               | Short-term   | 0.25 arc-sec / 25 mm |                      |                       |
|                                 | Overall  | 2.0 arc-sec          | 4.0 arc-sec          | 6.0 arc-sec           |
| Operating Pressure              |  | 80 psi (550 kPa) n   | ominal               |                       |
| Air Consumption                 |  | < 1.0 SCFM (28       | SLPM)                |                       |
| Air Quality                     | Clean (filtered to 1.0 µm or better)<br>Oil-free<br>Dry (-15 °C dew point) |                      |                      |                       |
| Construction                    | Hardcoat Aluminum<br>SS Fasteners  |                      |                      |                       |

Note: Precision specifications are dependent on load, orientation, and external forces on the bearing. Please consult PI for application-specific parameters.



#### **Ordering Example**

Part# <u>A-102.450</u> is a

Model: A-10 (Piglide RB linear air bearing)

Size: 2 (50x100mm table)

Travel: 450mm

| Δ | cc | Δe | so | ri | Δe |
|---|----|----|----|----|----|
| м | CC | es | รบ | rı | es |

Order the A10x-MNT mounting feet kit separately. Check the drawing and table on following page for dimensions.

x = size (1...9)

| Code | Travel (mm) |
|------|-------------|
| 50   | 50          |
| 100  | 100         |
| 150  | 150         |
| 200  | 200         |
| 300  | 300         |
| 450  | 450         |
| 600  | 600         |
| 750  | 750         |
| A00  | 1000        |

| Model | А   | В   | С   | D  | Е   | ш   | G   | Н    | J            | K     | L   | M  | N   | Р   | d   | R   | S      | Т  | ح    | V    | W  | Х         |
|-------|-----|-----|-----|----|-----|-----|-----|------|--------------|-------|-----|----|-----|-----|-----|-----|--------|----|------|------|----|-----------|
| A-101 | 50  | 50  | 35  | 15 | 25  | 5   | 15  | CL   | 4x M3 C'BORE | 2x M3 | 80  | 15 | 40  | N/A | N/A | 40  | 6x M3  | 12 | 21   | 30   | 10 | 4 (5/32") |
| A-102 | 100 | 50  | 45  | 25 | 25  | 5   | 15  | CL   | 4x M3 C'BORE | 2x M3 | 130 | 15 | 40  | 60  | N/A | 40  | 10x M3 | 12 | 46   | 40   | 10 | 6 (1/4")  |
| A-103 | 75  | 75  | 55  | 25 | 45  | 7.5 | 30  | 12.5 | 4x M5 C'BORE | 2x M5 | 115 | 35 | N/A | N/A | N/A | 60  | 4x M5  | 14 | 37.5 | 47.5 | 15 | 6 (1/4")  |
| A-104 | 115 | 75  | 75  | 45 | 45  | 7.5 | 30  | 12.5 | 4x M5 C'BORE | 2x M5 | 155 | 50 | N/A | N/A | N/A | 60  | 4x M5  | 14 | 57.5 | 67.5 | 15 | 6 (1/4")  |
| A-105 | 100 | 100 | 75  | 35 | 60  | 10  | 40  | 20   | 4x M6 C'BORE | 2x M6 | 150 | 50 | N/A | N/A | N/A | 80  | 4x M6  | 14 | 50   | 37.5 | 20 | 6 (1/4")  |
| A-106 | 150 | 100 | 100 | 60 | 60  | 10  | 40  | 20   | 4x M6 C'BORE | 2x M6 | 200 | 50 | N/A | 110 | N/A | 80  | 8x M6  | 14 | 75   | 50   | 20 | 6 (1/4")  |
| A-107 | 150 | 150 | 100 | 50 | 100 | 10  | 75  | 50   | 6x M6 C'BORE | 4x M6 | 200 | 50 | N/A | 110 | N/A | 125 | 8x M6  | 14 | 75   | 50   | 20 | 6 (1/4")  |
| A-108 | 200 | 200 | 130 | 70 | 140 | 10  | 100 | 50   | 6x M6 C'BORE | 4x M6 | 250 | 50 | N/A | 150 | N/A | 170 | 8x M6  | 14 | 100  | 65   | 20 | 6 (1/4")  |
| A-109 | 300 | 300 | 140 | 70 | 240 | 10  | 200 | 100  | 6x M6 C'BORE | 4x M6 | 350 | 50 | N/A | 150 | 250 | 270 | 12x M6 | 14 | 150  | 65   | 20 | 6 (1/4")  |



### Plglide HB: Hemispherical Air Bearing

FRICTIONLESS, IDEAL FOR ROTATIONAL MOTION IN THREE AXES



#### A-65X Series

- Clean room compatible
- Low intertia
- Diameters up to 300mm
- Freedom of rotation in three directions
- Load to 635kg
- Range of tip/tilt motion up to +/- 45 degrees
- Operating pressures from 30 to 90 psi
- Ideal for satellite attitude control testing and zero-g simulation

#### Overview

The Plglide HB series spherical air bearing enables unique positioning and simulation applications in both research and industrial fields. These bearings provide excellent load capacity and stiffness while allowing three axes of inherently frictionless rotational motion. Commonly used for zero-g satellite research, spherical bearings are also used in systems for precision chip bonding and optical alignment. Extremely rigid spindles can be made using a spherical bearing at each end of the spindle shaft. This arrangement also allows precision alignment of the spindle shaft on the fly by moving one spherical bearing relative to the other.

- Air preparation kit
- Mounting pedestals
- Custom configurations available upon request



|       |                     |                                  |                                      |      | ass<br>g) | Moment of                        |  |  |  |
|-------|---------------------|----------------------------------|--------------------------------------|------|-----------|----------------------------------|--|--|--|
| Model | Sphere Dia.<br>(mm) | Travel <sup>(2)</sup><br>(+/- °) | Load Capacity <sup>(1)</sup><br>(kg) | Base | Sphere    | Inertia <sup>(3)</sup><br>(g*m²) |  |  |  |
| A-651 | 50                  | 45                               | 15                                   | 115  | 70        | 0.02                             |  |  |  |
| A-652 | 75                  | 45                               | 35                                   | 235  | 215       | 0.15                             |  |  |  |
| A-653 | 100                 | 45                               | 65                                   | 550  | 475       | 0.6                              |  |  |  |
| A-654 | 150                 | 45                               | 160                                  | 1350 | 1475      | 4.5                              |  |  |  |
| A-655 | 200                 | 45                               | 265                                  | 2500 | 3350      | 18                               |  |  |  |
| A-656 | 250                 | 45                               | 405                                  | 4000 | 5525      | 48                               |  |  |  |
| A-657 | 300                 | 45                               | 635                                  | 6500 | 8100      | 103                              |  |  |  |

<sup>1.</sup> Load capacities listed assume supply pressure of 80 psi. Contact PI to determine load capacity if alternate supply pressures are required.

- 2. Other travels available upon request.
- 3. About the sphere center.

Operating Pressure: 80 psi (550 kPa) nominal, 90 psi maximum

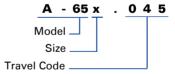
Air Consumption: < 1.0 SCFM (28 SLPM)

Air Quality: Clean (filtered to 1.0 µm or better) and oil-free

Dry (-15 °C dew point)

Materials: Hardcoat aluminum, stainless steel fasteners

Alternate materials available upon request



#### **Ordering Example**

Part# A-652.045 is a

Model: A-65 (Piglide HB hemispherical air bearing)

Size: 2 (75mm diameter hemisphere)

<u>Travel</u>: 045 (+/-45 degrees)

#### **Accessories**

Order the A65x-PED pedestal mounting kit separately.

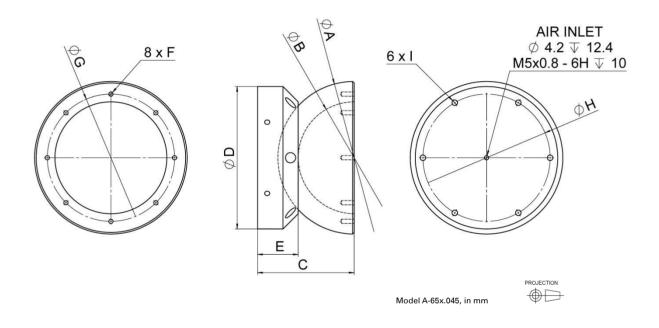
x = size (1...7)



Piglide HB Hemispherical Air Bearing, shown on optional pedestal mount; sold separately.

# $\mathbf{PI}$





| Model | А   | В   | С   | D   | Е  | F  | G   | Н  | 1   |
|-------|-----|-----|-----|-----|----|----|-----|----|-----|
| A-651 | 30  | 30  | 42  | 55  | 23 | М3 | 38  | M3 | 45  |
| A-652 | 50  | 50  | 55  | 70  | 27 | M3 | 60  | М3 | 60  |
| A-653 | 70  | 70  | 70  | 100 | 30 | M4 | 85  | M4 | 85  |
| A-654 | 110 | 110 | 95  | 140 | 40 | M5 | 125 | M5 | 125 |
| A-655 | 150 | 150 | 125 | 170 | 50 | M5 | 175 | M5 | 150 |
| A-656 | 200 | 200 | 150 | 210 | 55 | M6 | 225 | M6 | 190 |
| A-657 | 250 | 250 | 175 | 250 | 65 | M6 | 250 | M6 | 230 |



## PIMag®

### Magnetic Direct Drive Technology

Drive technology and control know-how as well as an expertise in bearings and encoders allow for a broad range of motors for system integration. Proprietary developments also include high-resolution force sensors for manufacturing and test equipment.

#### **Ironless Linear Motors**

- High acceleration and velocity
- Linear stages, planar scanners, PIMag® 6D positioning system
- Torque motors for rotation stages

#### **Voice Coil Drives**

- High dynamics for fast scanning and positioning
- OEM actuators, linear scanners, Hexapods
- Optional force sensors

#### **Drive Technology Beyond Standard**

- Highest accelerations up to 60g with resonance motor
- Highest force density for single phase linear motors with reluctance motor and cylindrical Halbach arrays
- High force density and low weight with linear Halbach arrays

#### **Guiding Systems**

- Plglide air bearings for frictionless motion and optimum straightness and flatness
- Active magnetic guidings align flatness during motion
- Flexure guidings provide frictionless motion over short strokes
- Ball and roller bearings from the leading suppliers







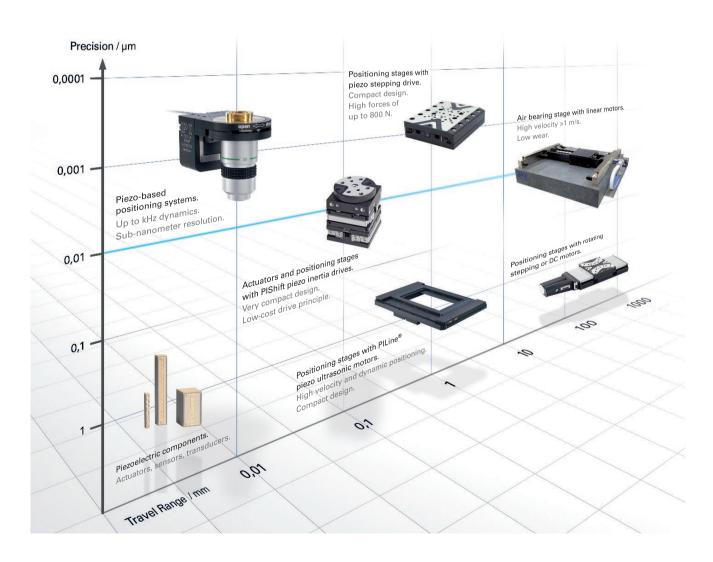
### Technology

### The Broadest and Deepest Portfolio

The technological scope of the PI Group is unique worldwide. PI develops, manufactures and qualifies all its core technologies itself. Thus PI is independent of components available on the market and offers individual solutions that go beyond the state of the art. Through its high measure of flexibility, PI plays a pioneering role in precision positioning and enables PI customers to benefit from distinct competitive advantages.

#### **Core Technologies**

- Piezo components, actuators and motors
- Magnetic drives
- Air bearing technology
- Guiding systems
- Nanometrology sensors
- Electronic amplifiers
- Digital controllers
- Software





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